

# LT-632 Turbidity Sensor

Self-Cleaning, Submersible Turbidity Sensor



# Pyxis Lab® Inc.

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**USER MANUAL** 

#### **Warranty Information**

#### Confidentiality

The information contained in this manual may be confidential and proprietary and is the property of Pyxis Lab, Inc. Information disclosed herein shall not be used to manufacture, construct, or otherwise reproduce the goods described. Information disclosed herein shall not be disclosed to others or made public in any manner without the express written consent of Pyxis Lab, Inc.

#### **Standard Limited Warranty**

Pyxis Lab warrants its products for defects in materials and workmanship. Pyxis Lab will, at its option, repair or replace instrument components that prove to be defective with new or remanufactured components (i.e., equivalent to new). The warranty set forth is exclusive and no other warranty, whether written or oral, is expressed or implied.

#### **Warranty Term**

The Pyxis warranty term is thirteen (13) months ex-works. In no event shall the standard limited warranty coverage extend beyond thirteen (13) months from original shipment date.

#### **Warranty Service**

Damaged or dysfunctional instruments may be returned to Pyxis for repair or replacement. In some instances, replacement instruments may be available for short duration loan or lease.

Pyxis warrants that any labor services provided shall conform to the reasonable standards of technical competency and performance effective at the time of delivery. All service interventions are to be reviewed and authorized as correct and complete at the completion of the service by a customer representative or designate. Pyxis warrants these services for 30 days after the authorization and will correct any qualifying deficiency in labor provided that the labor service deficiency is exactly related to the originating event. No other remedy, other than the provision of labor services, may be applicable.

Repair components (parts and materials), but not consumables, provided during a repair, or purchased individually, are warranted for 90 days ex-works for materials and workmanship. In no event will the incorporation of a warranted repair component into an instrument extend the whole instrument's warranty beyond its original term.

#### **Warranty Shipping**

A Repair Authorization (RA) Number must be obtained from Pyxis Technical Support before any product can be returned to the factory. Pyxis will pay freight charges to ship replacement or repaired products to the customer. The customer shall pay freight charges for returning products to Pyxis. Any product returned to the factory without an RA number will be returned to the customer. To receive an RMA you can generate a request on our website at <a href="https://www.pyxis-lab.com/request-return-or-repair/">https://www.pyxis-lab.com/request-return-or-repair/</a>

### **Pyxis Technical Support**

Contact Pyxis Technical Support at +1 (866) 203-8397 or service@pyxis-lab.com

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# 1 Introducing the Pyxis LT-632 Sensor

The LT-632 is a submersible, waterproof, self-cleaning sensor that utilizes dual wavelength detection technology to measure turbidity. The sensor automatically compensates for disturbances caused by flow fluctuations, climate change, color change or changes in turbidity. The instrument is virtually maintenance-free, and the self-cleaning capability of the sensor prevents deviations caused by air bubbles and suspended solids particulate. The LT-632 can be powered by a 24 VDC/6W power supply and offers fully integrated 4-20 mA and RS-485 Modbus output signals for connection to any controller, PLC or DCS network. When clean, the unique Pyxis sensor design offers a stability of <0.1 NTU for up to 1-year without calibration. Additionally, the LT-632 can be wirelessly accessed via the MA-CR Bluetooth adapter for local display, diagnostics, cleaning and calibration when using the uPyxis APP for mobile or desktop devices. The LT-632 is ideal for use in raw water, surface water, storm water, process water and discharged water applications.

# 1.1 Features

The LT-632 includes the following features:

- Resolution as low as 2 NTU
- Built-in transmitter, without preamplifier or meter head
- Combination 4-20mA isolated signal and RS-485 Modbus (RTU) output
- Simple / Wireless calibration using uPyxis Mobile or Desktop APPs and MA-CR Bluetooth Adapter
- Supports self-cleaning of sensor lens for dirty water applications
- Optional calibration with Pyxis Formazine calibration standards or field water samples
- ¾-inch MNPT Threaded For Fixed Submersion

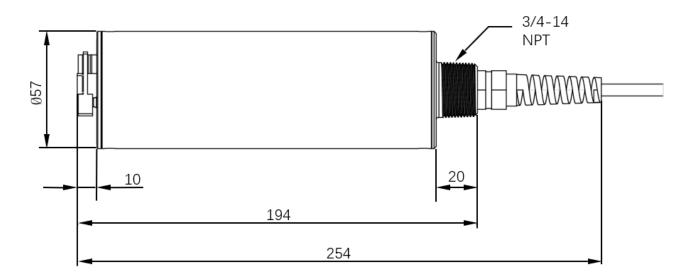


Figure 1 LT-632 Dimensions (mm)

# 1.2 Specifications

Item	LT-632		
P/N	53250		
Parameter	Turbidity		
Measurement Range (4-20mA Output Scale)	0.00 – 1000.00		
Unit of Measure	NTU Nephelometric Turbidity Unit		
Lower Detection Limit	0.5NTU		
Precision	± 2 NTU or 2% of the value		
Accuracy	± 2 NTU or 3% of the value		
Resolution	0.1NTU		
Response Time	T95<12 Seconds		
Calibration Method	Field Tested Process Sample or Formazine Calibration Standard		
Dual Wavelength	Warm White Light <100 NTU / Infrared Light >1000 NTU		
Method	Scattering		
Power Supply	22 – 26VDC 6W		
Operating Temperature	32 – 122 °F (0-50 °C)		
Storage Temperature	-7 °C – 60 °C (20 – 140 °F)		
Outputs	Isolated 4 – 20 mA Analog Output & Isolated RS-485 Digital Output		
	Submersed – Fixed Conduit ¾-inch MPNT Threaded Cable Fitting		
Installation	Submersed – Hoisting Chain or Cable		
	Sensor Distance from Bottom of Vessel (>15cm)		
	Sensor Distance from Sides of Vessel (>10cm)		
Material	316 Stainless Steel – Body & Wiper Arm		
Waterial	PTFE – Wiper Blade		
Weight	1,530 g (3.3 lbs.)		
Operational Pressure	45 psi (3.1 Bar)		
Rating	IP-68, Fully Dustproof & Waterproof		
Regulation	CE / RoHS		
Dimension (L x W x H)	(254mm x 57mm x 57mm)		
Cable Length	33 feet (10m) w/IP-67 8-Pin adapter		
Cable Leffgill	4.9 feet (1.5m) flying lead w/IP-67 8-Pin adapter		
	(Extension Cables Also Available)		

<sup>\*</sup>Pyxis Lab specifications are subject to change without notice

# 1.3 Unpacking the Pyxis LT-632 Series Sensor

Remove the instrument and accessories from the shipping container and inspect each item for any damage that may have occurred during shipping. Verify that all items listed on the packing slip are included. If any items are missing or damaged, please contact Pyxis Customer Service at <a href="mailto:service@pyxis-lab.com">service@pyxis-lab.com</a>

# 1.4 Standard Accessories

The following accessories are included in the LT-632 sensor package (P/N: 53250)

- One LT-632 sensor with bulkhead terminated cable w/8-Pin Female Adapter (33 feet / 10m)
- One MA-1.5CR Flying Lead Cable w/8-Pin Male Adapter/Flying Lead (4.9 feet / 1.5m)
- The full instrument manual is available for download at www.pyxis-lab.com/shop/



Figure 2 - LT-632 Sensor with 10m Terminated Cable + 1.5m Flying Lead Cable (MA-1.5CR)

# 1.5 Optional Accessories

The following optional accessories can be purchased order@pyxis-lab.com or www.pyxis-lab.com/shop/

Accessory Name	Item Number
LT-632 Replacement Wiper Blade/Arm Assembly Kit (Includes 5 sets of Wiper Blade with Arm)	50700-A50
MA-CR (Bluetooth Adapter/Display For use with Pyxis 8-Pin Sensors)	MA-CR
MA-NEB (USB Bluetooth Adapter for use with Laptop or Desktop)	MA-NEB
MA-120-C Fixed Submersion Adapter Bracket (Submersed Fixed Installation Mounting Bracket)	50700-A11
MA-50CR (50' Extension Cable w/8Pin Adapter)	50743
MA-100CR (100' Extension Cable w/8Pin Adapter)	50744
Formazine Turbidity Calibration Standard – 100 NTU (4,000 mL)	57010-100L
Formazine Turbidity Calibration Standard – 200 NTU (4,000 mL)	57010-200L
Formazine Turbidity Calibration Standard – 500 NTU (4,000 mL)	57010-500L





LT-632 Turbidity Sensor Operation Manual

# 2 Quick 4-20mA Start

Follow the wiring table below to connect the LT-632 sensor to a controller or PLC. \*NOTE\* All Pyxis sensors provide a passive 4-20mA output signal, they are NOT LOOP POWERED. 24VDC+ power supply and 4-20mA+ signal are independent of each other in all Pyxis Lab sensors.

Color	Designation
Brown	Power GND
Green	RS-485 C
Yellow	RS-485 B
Gray*	4-20mA - (Internally connected to power ground)
Pink	Not Used
Blue	RS-485 A
White	4-20mA + <i>(Turbidity NTU)</i>
Red	24V+
Silver	PE

\*NOTE\* The 24V- power ground (brown) and the 4-20 mA- (gray) return are internally connected. If the 24V- power ground and the 4-20 mA return in the controller are internally connected (non-isolated 4-20mA input), it is unnecessary to connect the 4-20 mA- (gray wire) to the 4-20 mA negative terminal in the controller. If a separate DC power supplier other than that from the controller is used, make sure that the output from the power supply is rated for 22-26 VDC @ 250mA.

Please refer to the table below for proper LT-632 input 4-20mA scaling in your receiving display, controller or PLC.

LT-632 Output Scaling (4-20mA)			
mA	Value	Units	
4	0	NTU	
20	1000	NTU	

# 3 Installation

**Submersed Fixed Installation with MA-120-C**: The LT-632 may be installed in a submersed/fixed application using the MA-120-C Submersion Adapter Mounting Bracket (P/N: 50700A11). The LT-632 sensor should be installed as outlined in and 3A. For installation, the MA-120-C bracket should permanently mounted in a fixed position for easy access to the LT-632 sensor and piping. For sensor replacement and maintenance, users only need to lift (vertically/upwards) the sliding block and conduit with the mounted sensor from MA-120-C bracket. \*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water vessel to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides. Please note the LT-632 outer diameter is ¾ - inch NPT. A ¾ to 1-inch NPT bushing is required for installation.

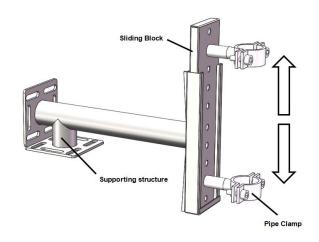


Figure 3 – MA-120-C Submersion Adapter Mounting Bracket

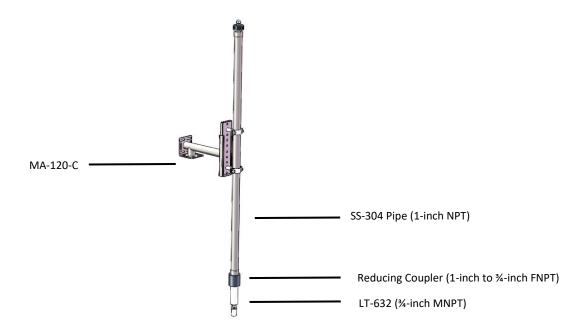


Figure 3A - Installation Using MA-120-C Submersion Bracket with Piping

**Submersed Installation with Lifting Ring:** The LT-632 sensor comes equipped with a lifting ring which allows the sensor to be lifted and lowered using a user provided chain or cable. For this method of installation and use, please refer to figure. For sensor replacement and maintenance, users only need to lift the chain or cable and LT-632 sensor vertically (upwards).

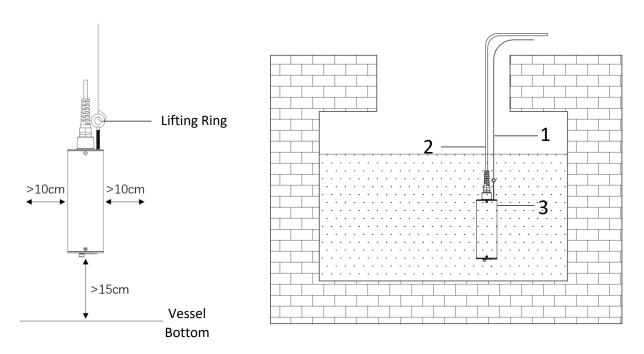


Figure 4 - Submersed Installation Using the Lifting Ring

\*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water vessel to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides.

Reference ID	Name
1	Retention Chain / Cable
2	Sensor Output Cable
3	LT-632 Turbidity Sensor

# 4 Calibration and Diagnosis

The LT-632 turbidity sensor is rigorously calibrated before leaving the factory. As such, users do not need to calibrate the sensor for a period of one year if the sensor is maintained clean. Users can however calibrate the sensor according to their needs and as desired using the MA-CR Bluetooth adapter and uPyxis APP for mobile or desktop devices. Likewise, the LT-632 may also be calibrated after cleaning via PLC or controller through 4-20mA communication.



# 4.1 Calibration and Diagnosis by uPyxis Mobile APP

Connect and power the LT-632 sensor to a display, controller or PLC. Insert the Pyxis MA-CR Bluetooth adapter (P/N: MA-CR) as shown in the following connection diagram, using the 8-pin adapters on the provided sensor cables. (Figure ). The power should be sourced from a 24 VDC power terminal of the connected display, controller or PLC. If a controller is not available, the LT-632 may also be powered via any 22-26 VDC power supply capable of 6W, that can directly connect to the LT-632 sensor with provided connection cables from Pyxis. \*NOTE\* The MA-CR provides a micro-display for local visibility of the sensor reading and mA value output.



Figure 5 - LT-632 and MA-CR Bluetooth Adapter Powered By Connected Display, Controller or PLC

Download and install the uPyxis APP from Apple Store or Google Play per the QR codes provided in the image above. Be sure to turn on Bluetooth in the mobile device (please do not pair the device Bluetooth to any Pyxis device, the uPyxis APP will do the pairing). Open the uPyxis APP in the mobile device. Finger swipe the screen downward to refresh the screen and scan for the available Pyxis Bluetooth devices. The discovered devices will be listed (see Figure 6).



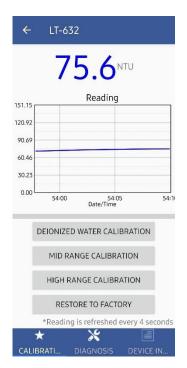


Figure 6 Figure 7

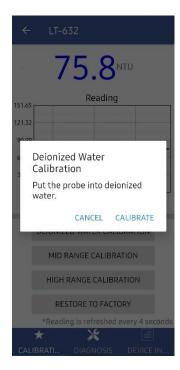
Tap the discovered LT-632 series sensor to connect to it via Bluetooth. The uPyxis APP can identify the sensor type if multiple Pyxis sensors are discovered in the scan.

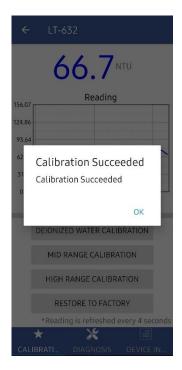
As shown in Figure 7, when connected via the MA-CR Bluetooth adapter, the uPyxis calibration page will display the current turbidity concentration value being measured by the LT-632 sensor connected. Four functional tabs are available in this page: <u>Deionized Water Calibration</u>, <u>Mid-Range Calibration</u>, <u>High-Range Calibration</u>, and <u>Restore to Factory</u>.

# 4.1.1 Calibration by uPyxis Mobile APP

<u>Deionized Water Calibration Process</u> - Remove the LT-632 sensor and rinse it thoroughly with deionized water. Repeat this rinse process three times. Wipe the sensor with a dust-free cloth or paper-towel to confirm that the sensor is free of obvious impurities. Insert the sensor into an oversized beaker or bucket. Add bubble-free deionized water or water with <1.0NTU of turbidity container and wait for the sensor reading to stabilize. Click the "Deionized Water Calibration" button after the reading stabilizes. If the calibration is successful, the interface will return a message "Calibration Succeeded" as shown in Figure 9. If the calibration has failed, the interface will return a message "Calibration Failed", as shown in Figure 10 and the user must repeat the process until calibration success is achieved.

\*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water container to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides.





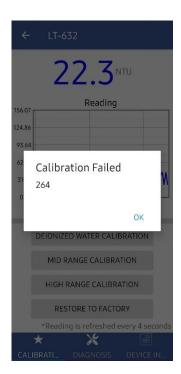


Figure 8 Figure 9 Figure 10

Mid-Range Calibration Process – After completing Deionized Water Calibration, remove and insert the LT-632 sensor into a clean and dry oversized beaker or bucket and add the midpoint calibration solution. \*NOTE\* The midpoint calibration solution can be process water of the application itself, with a test confirmed turbidity value in the range of 20 to 120 NTU, or users may also use Formazine calibration standard solution. Wait until the reading stabilizes and then click the Midpoint Calibration button to calibrate the midpoint to the value of the standard utilized, as shown in Figure 11. If the calibration is successful, the interface will return a message "Calibration Succeeded". If the calibration has failed, the interface will return a message "Calibration Failed" and the user must repeat the process until calibration success is achieved.

High-Range Calibration Process - If the high range calibration is not required (>200NTU), the user does not need to calibrate the high range. To continue with the high range calibration after completing Mid-Range calibration, remove and insert the LT-632 sensor into a clean and dry beaker and inject the High Point calibration solution. \*NOTE\* The high point calibration solution can be process water of the application itself, with a test confirmed turbidity value in the range of 200 to 1,000 NTU, or users may also use Formazine calibration standard solution. Wait until the reading stabilizes and then click the High Point Calibration button to calibrate the highpoint to the value of the standard utilized, as in Figure 12. If the calibration is successful, the interface will return a message "Calibration Succeeded". If the calibration has failed, the interface will return a message "Calibration Failed" and the user must repeat the process until calibration success is achieved.

\*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water container to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides.



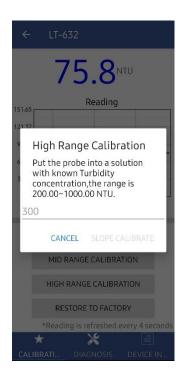


Figure 11

Figure 12

#### **Trouble Shooting Steps for Failed Calibration Messages**

- The Deionized water has not been contaminated. 0
- The standard solution is accurately pre-measured to verify turbidity. 0
- The sensor is clean and not contaminated with debris or other materials.

#### **Restore to Factory Calibration Settings**

Restore To Factory Calibration Settings – If user wants to restore the sensor calibration to factory default parameters, as shown in Figure 13, click the OK option to confirm. If the restoration is successful, the interface will return a message "Restore Succeed" (Figure 14).

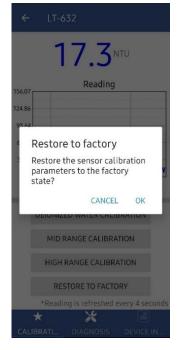


Figure 13

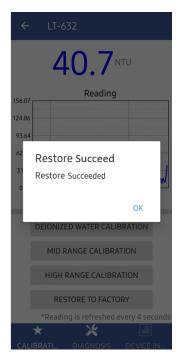


Figure14

# 4.1.3 Diagnosis

Tap Diagnosis in the bottom of the APP page to launch the diagnosis page (Figure 15).



Figure 15 - Select Diagnosis for Sensor

<u>Export/Upload Sensor Diagnosis Data</u> - In this page, the raw data measured by the sensor is displayed. To help troubleshooting possible issues with the sensor, please save images of these data when the sensor is respectively placed in a clean water (tap water or deionized water), in a known Formazine Turbidity Calibration Standard Solution and/or in the sample that the sensor is intended for. This data may be exported from the uPyxis APP via email to <a href="mailto:service@pyxis-lab.com">service@pyxis-lab.com</a> for technical support.

# 4.1.4 Cleaning Period Adjustment

Tap Device info in the bottom of the uPyxis APP page to launch the Device info page (Figure ). You can set the **Device Name, Product Name, Modbus Address** and **Brush Setting** for the LT-632 sensor. Press **Brush Once** to activate the wiper arm manually. Be sure to press **Apply Settings** to save any changes.

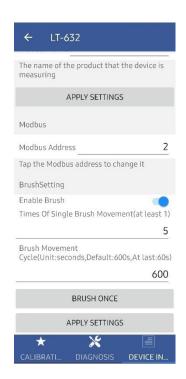


Figure 16 - Cleaning Period Adjustment

# 4.2 Calibration and Diagnosis by uPyxis Desktop APP

Download and install uPyxis Desktop APP on your PC or Laptop from





Connect and power the LT-632 sensor to a display, controller or PLC. Insert the Pyxis MA-CR Bluetooth adapter (P/N: MA-CR) as shown in the following connection diagram, using the 8-pin adapters on the provided sensor cables. (Figure 17). Insert the MA-NEB Bluetooth USB adapter (P/N: MA-NEB) into the USB port of your PC or Laptop according to connection diagram below (Figure 17).



Figure 17 - Connect the LT-632 to a computer via Pyxis MA-CR and MA-NEB adapter

Establish connection between uPyxis Desktop APP and the LT-632 through the following steps:

- 1. Open the desktop **uPyxis Desktop** APP on your PC or Laptop.
- 2. Click **Device** to launch the connection option menu.
- 3. Select Connect via USB-Bluetooth (Figure 18).
- 4. Select the Comm Port to make a connection (Figure 19) normally only one Comm port is identified by uPyxis. If more than one Comm port listed in the selection dropdown, you may try to select each one to see if a connection can be made. Alternatively, you may use the Windows Device Manager to identify the Comm Port that the Pyxis USB adapter is used.

After the connection is established, the LT-632 sensor series number and current turbidity concentration reading of the water will be displayed on the left of the information page (Figure ). In this page, you can set the **Device Name, Product Name, Modbus Address** and **Brush Setting** for the device. Click Calibration to launch the calibration (Figure 21).

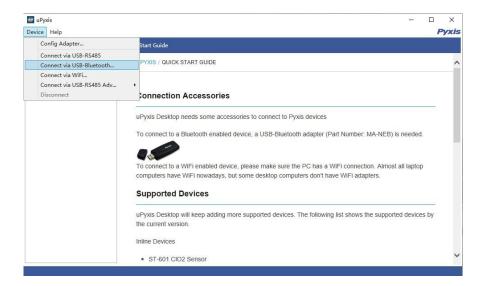


Figure 18 - Connection Options

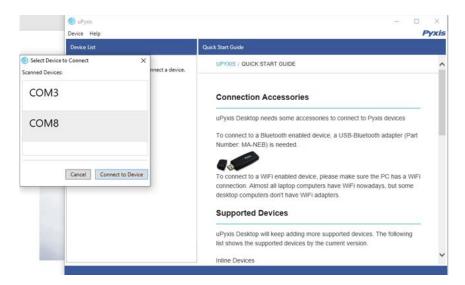


Figure 19 - Select a Comm Port



Figure 20 - Connected to a LT-632 sensor and information page

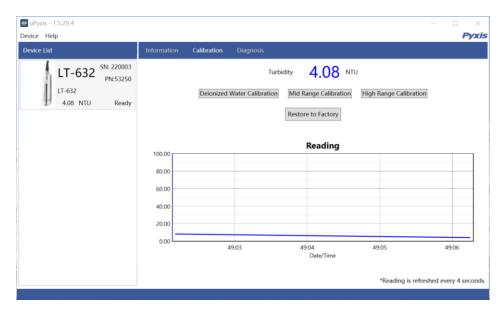


Figure 21 - Calibration Page

#### 4.2.1 Calibration

<u>Deionized Water Calibration Process</u> - Remove the LT-632 sensor and rinse it thoroughly with deionized water. Repeat this rinse process three times. Wipe the sensor with a dust-free cloth or paper-towel to confirm that the sensor is free of obvious impurities. Insert the sensor into an oversized beaker or bucket. Add bubble-free deionized water or water with <1.0NTU of turbidity container and wait for the sensor reading to stabilize. Click the "Deionized Water Calibration" button after the reading stabilizes. If the calibration is successful, the interface will return a message "Calibration Succeeded" as shown in Figure 9. If the calibration has failed, the interface will return a message "Calibration Failed", as shown in Figure 10 and the user must repeat the process until calibration success is achieved.

\*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water container to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides.



Figure 22 - Deionized Water Calibration

Mid-Range Calibration Process – After completing Deionized Water Calibration, remove and insert the LT-632 sensor into a clean and dry oversized beaker or bucket and add the midpoint calibration solution. \*NOTE\* The midpoint calibration solution can be process water of the application itself, with a test confirmed turbidity value in the range of 20 to 120 NTU, or users may also use Formazine calibration standard solution. Wait until the reading stabilizes and then click the Midpoint Calibration button to calibrate the midpoint to the value of the standard utilized, as shown in Figure 11. If the calibration is successful, the interface will return a message "Calibration Succeeded". If the calibration has failed, the interface will return a message "Calibration Failed" and the user must repeat the process until calibration success is achieved.

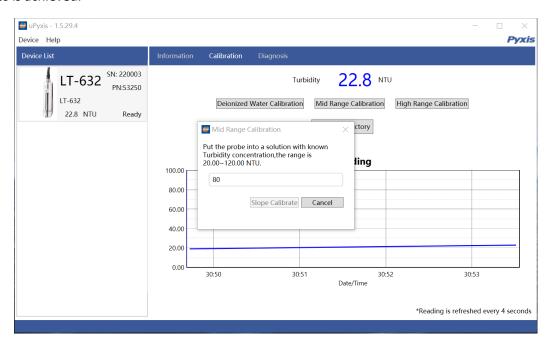


Figure 23 - Mid-Range Calibration

<u>High-Range Calibration Process</u> - If the high range calibration is not required (>200NTU), the user does not need to calibrate the high range. To continue with the high range calibration after completing Mid-Range calibration, remove and insert the LT-632 sensor into a clean and dry beaker and inject the High Point calibration solution. \*NOTE\* The high point calibration solution can be process water of the application itself, with a test confirmed turbidity value in the range of 200 to 1,000 NTU, or users may also use Formazine calibration standard solution. Wait until the reading stabilizes and then click the High Point Calibration button to calibrate the highpoint to the value of the standard utilized, as in Figure 12. If the calibration is successful, the interface will return a message "Calibration Succeeded". If the calibration has failed, the interface will return a message "Calibration Failed" and the user must repeat the process until calibration success is achieved.

\*NOTE\* The LT-632 should be installed with a minimum distance of >15cm from the bottom of water container to the lens of the sensor and a minimum of >10cm from the vessel wall on all sides.

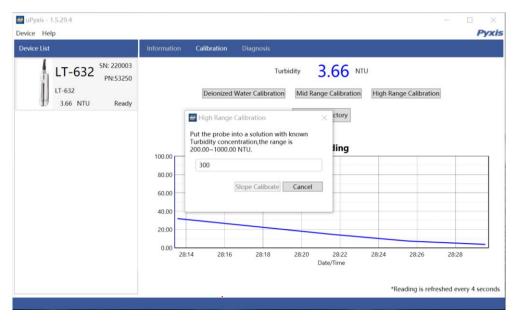


Figure 24 - High-Range Calibration

# <u>Trouble Shooting Steps for Failed Calibration Messages</u>

- The Deionized water has not been contaminated.
- The standard solution is accurately pre-measured to verify turbidity.
- The sensor is clean and not contaminated with debris or other materials.

### 4.2.2 Restore to Factory

<u>Restore To Factory Calibration Settings</u> – If user wants to restore the sensor calibration to factory default parameters, click the OK option to confirm. If the restoration is successful, the interface will return a message "Restore Succeed" (Figure 25).

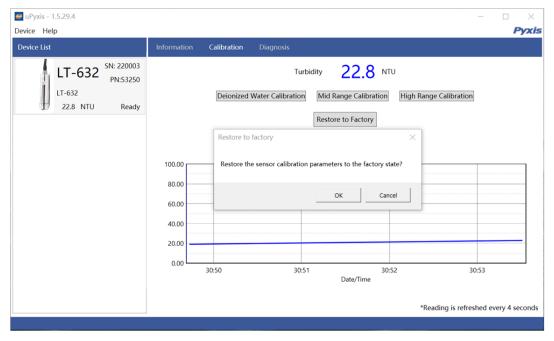


Figure 25 - Restore to Factory

# 4.2.3 Diagnosis

<u>Export/Upload Sensor Diagnosis Data</u> - In this page, the raw data measured by the sensor is displayed. To help troubleshooting possible issues with the sensor, please save images of these data when the sensor is respectively placed in a clean water (tap water or deionized water), in a known Formazine Turbidity Calibration Standard Solution and/or in the sample that the sensor is intended for. This data may be exported from the uPyxis APP via email to <a href="mailto:service@pyxis-lab.com">service@pyxis-lab.com</a> for technical support.

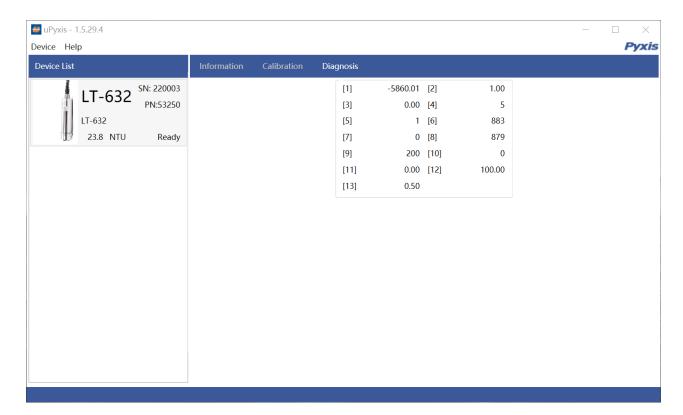


Figure 26 - Select Diagnosis Condition

# 4.2.4 Cleaning Period Adjustment

In information page, you can set the **Device Name, Product Name, Modbus Address** and **Brush Setting** for the LT-632 sensor. Press **Brush Once** to activate the wiper arm manually. Be sure to press **Apply Settings** to save any changes.

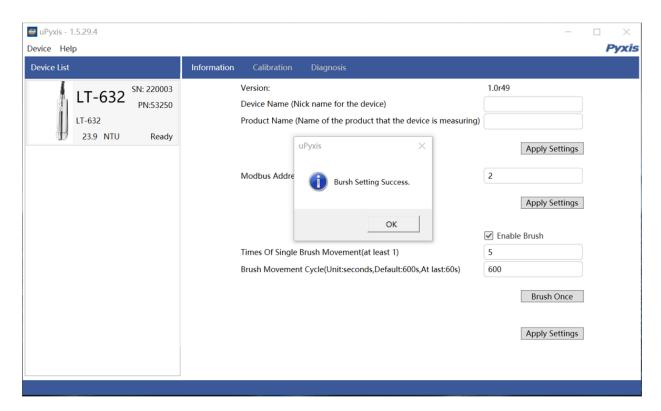


Figure 27 -Cleaning Period Adjustment

# 5 Modbus RTU

The LT-632 sensor is configured as a Modbus slave device. In addition to the turbidity value, other operational parameters, including warning and error messages, are available via a Modbus RTU connection. Contact Pyxis Lab Customer Service <a href="mailto:service@pyxis-lab.com">service@pyxis-lab.com</a> for more information.

# 6 Sensor Cleaning and Maintenance

The LT-632 sensor is designed to provide reliable and continuous turbidity readings. Although a self-cleaning feature has been added, heavy fouling can prevent light from reaching the sensor and may affect the accuracy of the sensor, depending on application conditions.

The LT-632 sensor is designed to be easily removed, inspected and cleaned if required.

Aged heavy deposition, especially inorganic deposits such as iron oxide and calcium carbonate, can be removed by submersing and soaking (15 minutes) the LT-632 sensor into the Pyxis Sensor Cleaning Solution Kit available from Pyxis online Estore/Catalog <a href="https://www.pyxis-lab.com/product/inline-sensor-cleaning-kit/">https://www.pyxis-lab.com/product/inline-sensor-cleaning-kit/</a>



Figure 28 – Pyxis Probe Cleaning Solution Kit (P/N: SER-01)

# **Sensor Wiper Replacement Instructions**

Replacement of wiper arm assembly is outlined below.

- **Step 1** Set the wiper arm assembly to a horizontal position after powering off the sensor.
- **Step 2** Remove the M2 screw that holds the wiper arm assembly nut.
- **Step 3** Remove the old wiper arm assembly.
- **Step 4** Install the wiper arm assembly to the sensor.
- **Step 5** Install the new M2 screw into the nut.



Figure 29 Set wiper arm to horizontal position



Figure 30 Remove the M2 screw



Figure 31 Remove the old wiper arm



Figure 32 Install the new wiper arm



Figure 33 Install the new M2 screw into the new wiper arm nut

# 8 Contact Us

Contact us if you have questions about the use or maintenance of the LT-632 sensors:

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